

# OMERO & Atlas Informatics

Bill Hill  
MRC Human Genetics Unit,  
MRC IGMM, University of Edinburgh,  
EH4 2XU, UK  
[Bill.Hill@igmm.ed.ac.uk](mailto:Bill.Hill@igmm.ed.ac.uk)

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# Overview

Context

Woolz

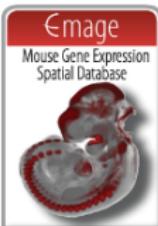
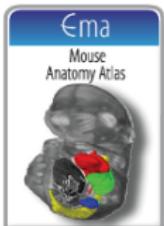
IIP3D

Transformations

Aspirations

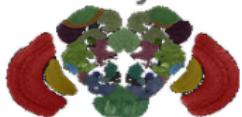
# Context

[www.emouseatlas.org](http://www.emouseatlas.org)



The e-Mouse Atlas Project

Virtual Fly Brain



[www.gudmap.org](http://www.gudmap.org)



DMDD



Eurexpress

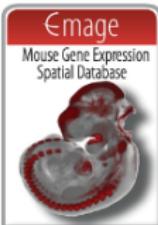
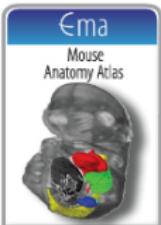


EmbryExpress



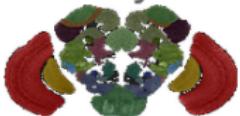
# Context

[www.emouseatlas.org](http://www.emouseatlas.org)



The e-Mouse Atlas Project

Virtual Fly Brain



**DMDD**

**eChickAtlas**

**Eurexpress**



*EmbryoExpress*



# Woolz 1/2 - Origins (1980s)

FIP - Fast Interval Processor

Metaphase finding,  
cervical and lung  
cancer screening, ...

Hardware → Software



# Woolz 2/2 - Domains and Values

object ← { type  
linkcount  
domain  
values  
properties }

spatial domains,  
conforming meshes,

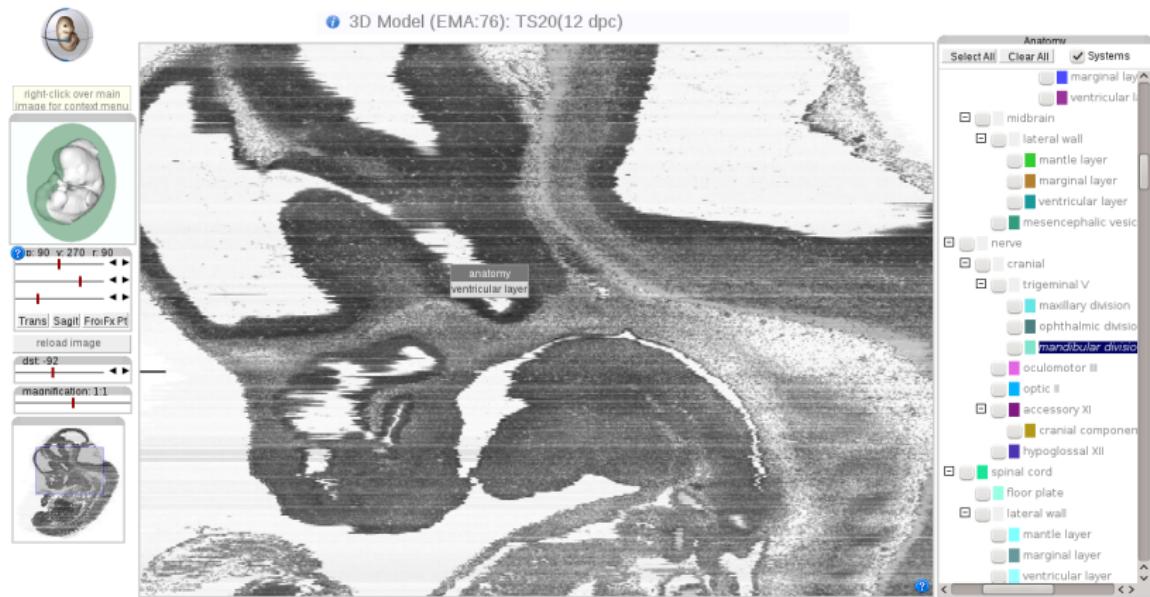
...

(memory mapped)  
values, mesh data,

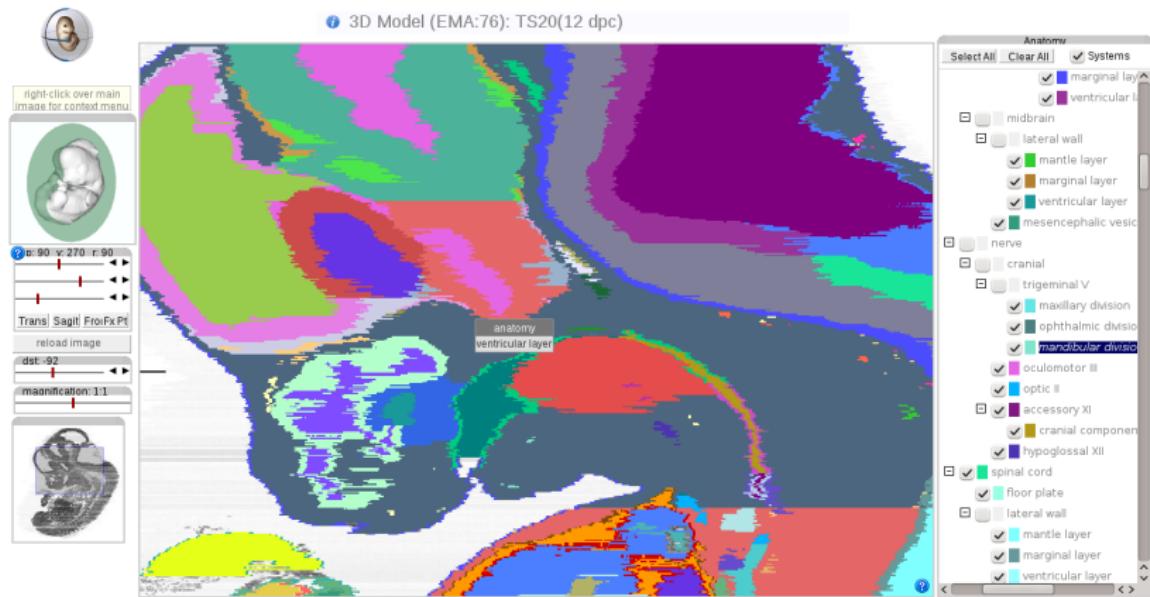
Object Types:

- ▶ Images
- ▶ Ancillary data (such as provenance)
- ▶ Annotation
- ▶ Boundaries, surface meshes and geometric models
- ▶ Conforming meshes
- ▶ Compound objects built from other objects
- ▶ Histograms and look up tables
- ▶ Transforms basis function, mesh, section

# IIP3D 1/5 - Example Application



# IIP3D 1/5 - Example Application



# IIP3D 2/5 - The IIP3D Protocol

Requests have 4 components

`http://a.b.c/cgi-bin/wlziipsrv.cgi? WLZ=/obj/a.wlz & DST=4 & QLT=50 & PTL-0,3`

Server address

Resource specifier

Parameters

Information request

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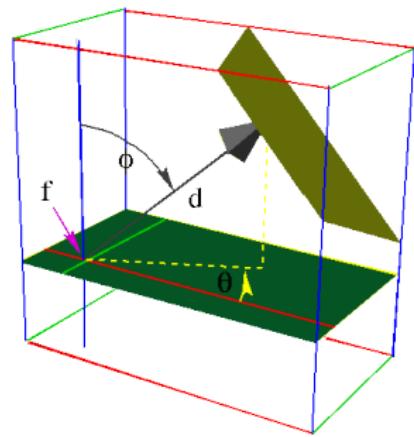
Resource specifier

Parameters

★ Information request

# IIP3D 3/5 - The IIP3D Protocol

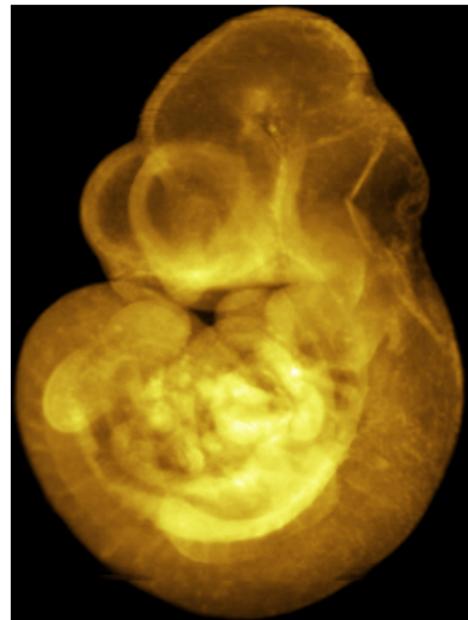
<b>DST</b>	- distance of the sectioning plane
<b>FXP</b>	- fixed point of the viewing section (1)
<b>FXT</b>	- fixed point of the viewing section (2)
<b>MOD</b>	- projection mode
<b>PIT</b>	- pitch angle of the section plane
<b>ROL</b>	- roll angle of the section plane
<b>SCL</b>	- scale used in sectioning
<b>UPV</b>	- up vector for the section plane
<b>YAW</b>	- yaw angle of the section plane



<b>SEL</b>	- component selection and morphological operations
<b>MAP</b>	- image value remapping
<b>RMD</b>	- rendering mode (section   projection)

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# IIP3D 4/5 - Server & Client

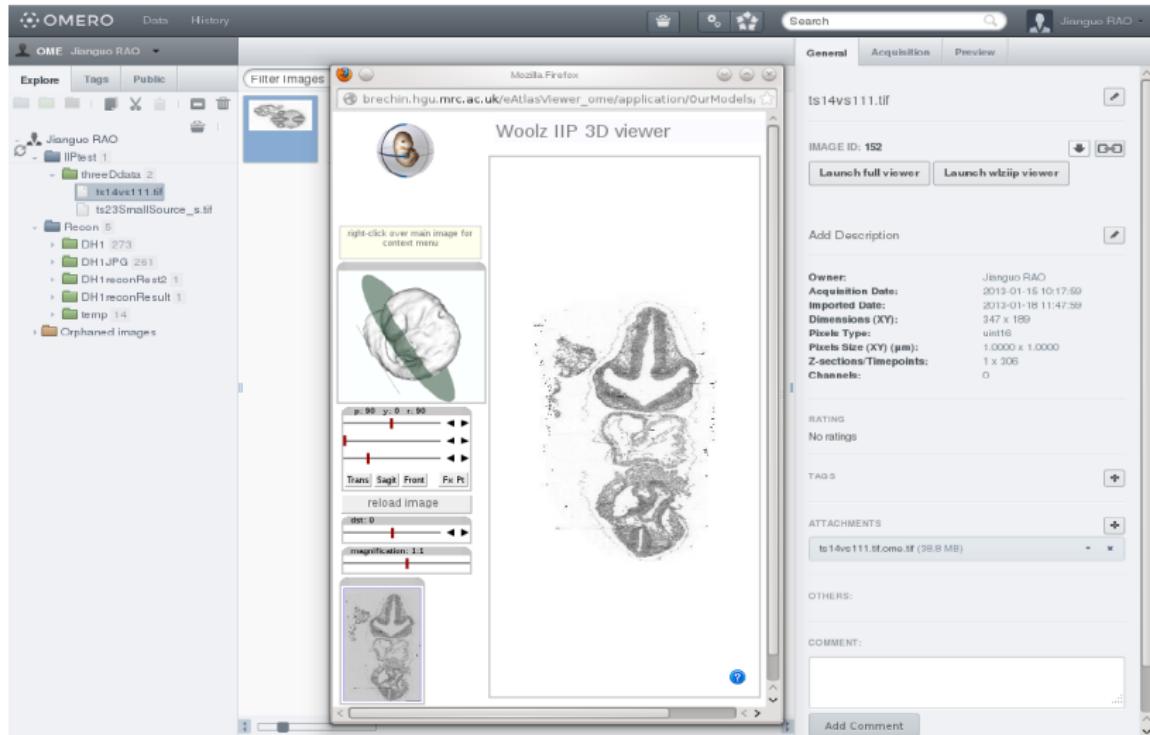
Woolz objects with multiple channels composited on the server to tiles.

Memory mapped values for large size and number of objects.

Browser based IIP3D clients using HTML5.

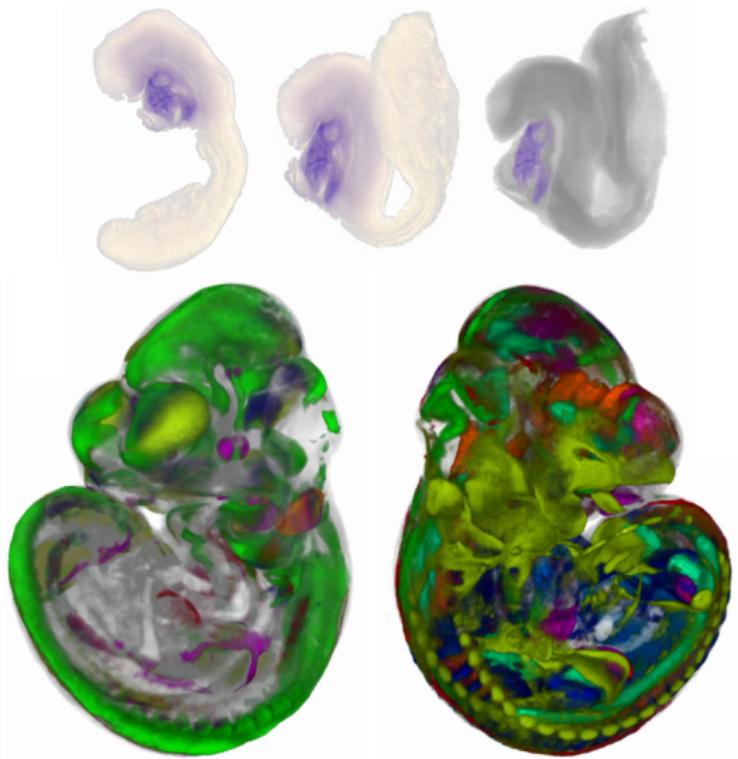
Object queries.

# IIP3D 5/5 - Integration with OMERO



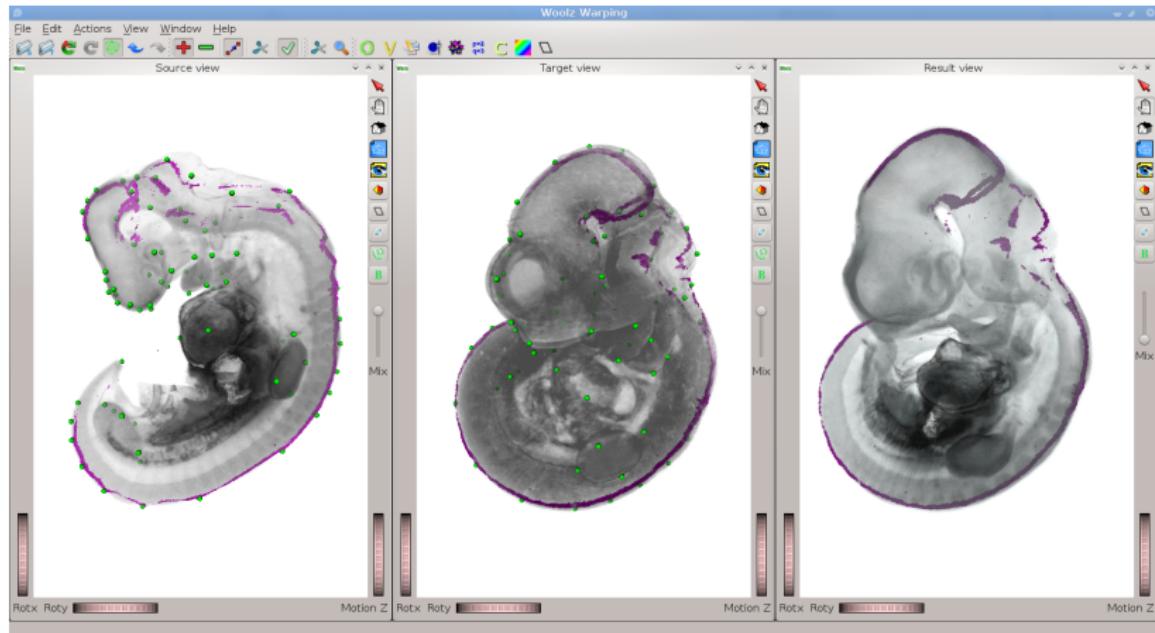
# Transformations 1/2 - Examples

EMAGE



# Transformations 1/2 - Examples

HUDSEN CS14 → EMAGE TS17



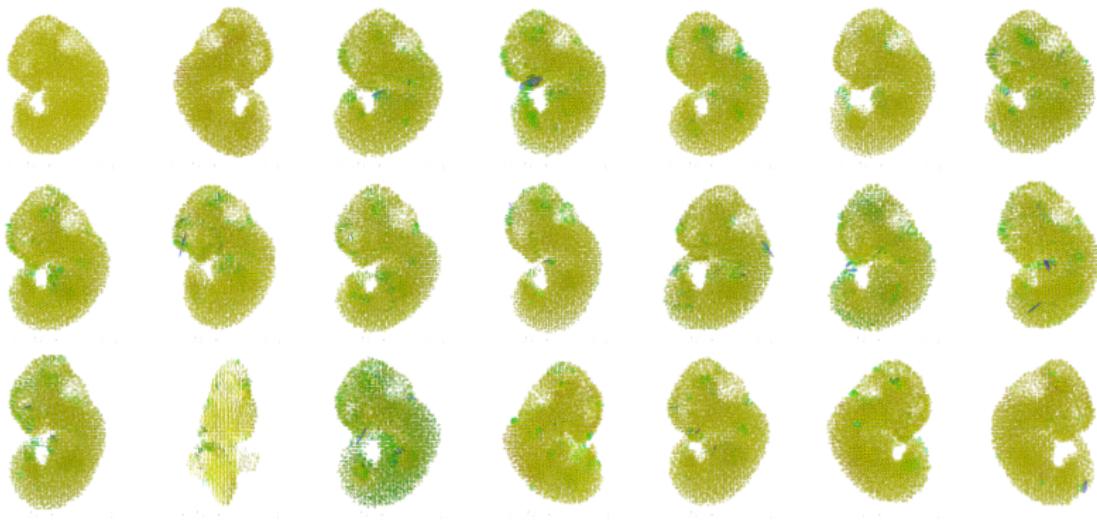
# Transformations 2/2 - More Examples

CS14 → TS17



# Transformations 2/2 - More Examples

TS17 Population



# Aspirations

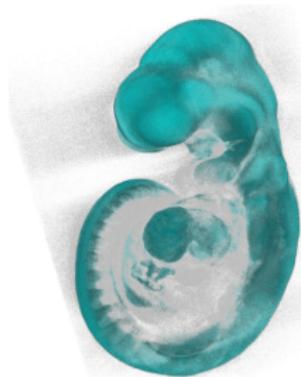
Extend use of OMERO

OMERO FS & Woolz objects

# Acknowledgements & Links

- ▶ Richard Baldock, Jianguo Rao
- ▶ EMAGE & EMAP (<http://www.emouseatlas.org>)
- ▶ GUDMAP (<http://www.gudmap.org/>)
- ▶ Hudsen (<http://www.hudsen.org/>)
- ▶ Virtual Fly Brain (<http://www.virtualflybrain.org>)
- ▶ Source (<https://github.com/ma-tech>)

# Woolz Efficiency



Unsigned byte cuboid image 372x279x512  
(57MB),

Woolz object after threshold 7.7MB

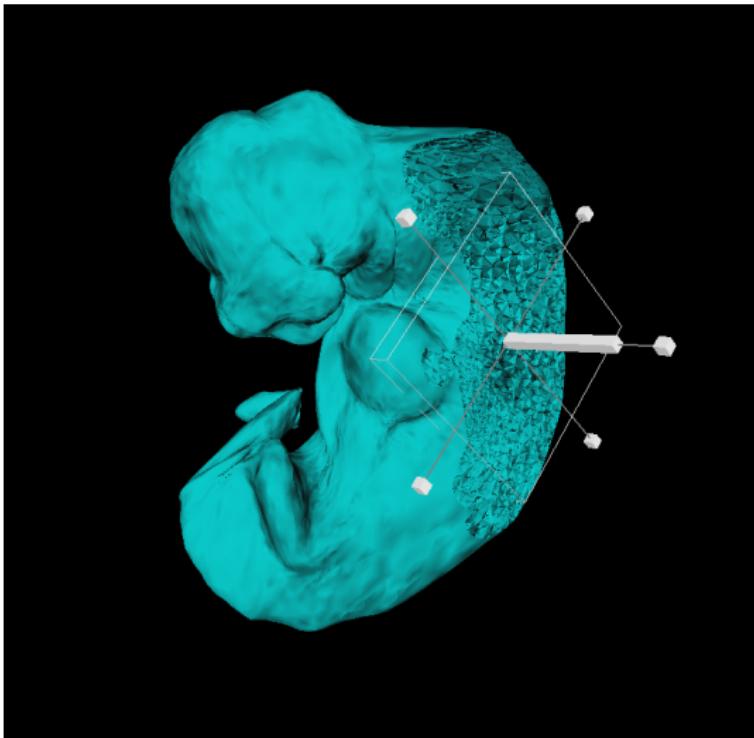
Woolz domain after threshold 2.9MB

	time (ms)			
	Woolz	ITK	imagej	MATLAB
image threshold ( $\geq 32$ )	34	62	-	-
dilation (C26)	31 (C26)	-	407 (C8)	-
dilation (sphere r=3)	120	3110	-	-
intersection	11	56	-	102

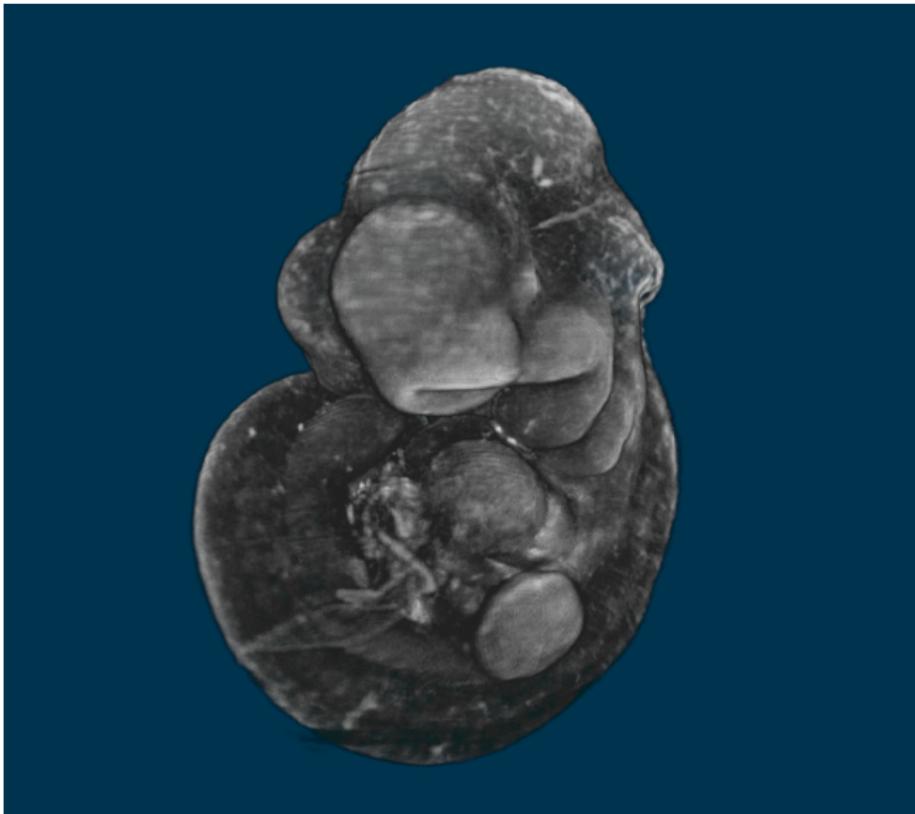
All times for 3.4 GHz Intel i7-2600 quad core CPU

# Woolz Conforming Meshes

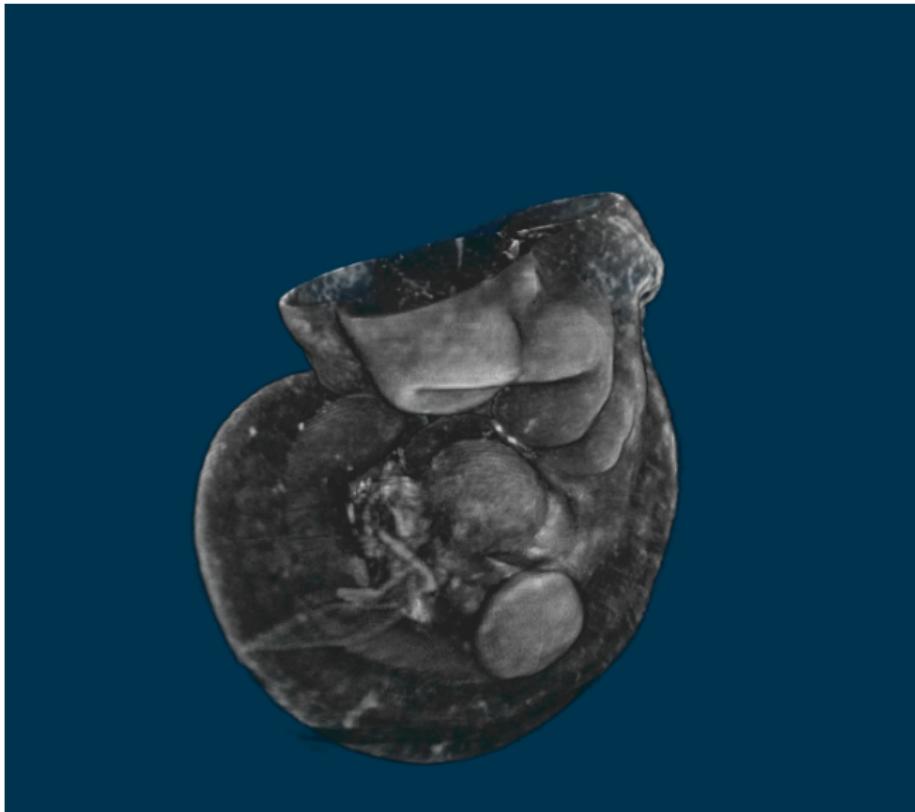
TS17 conforming mesh (62616 nod, 316141 elm)



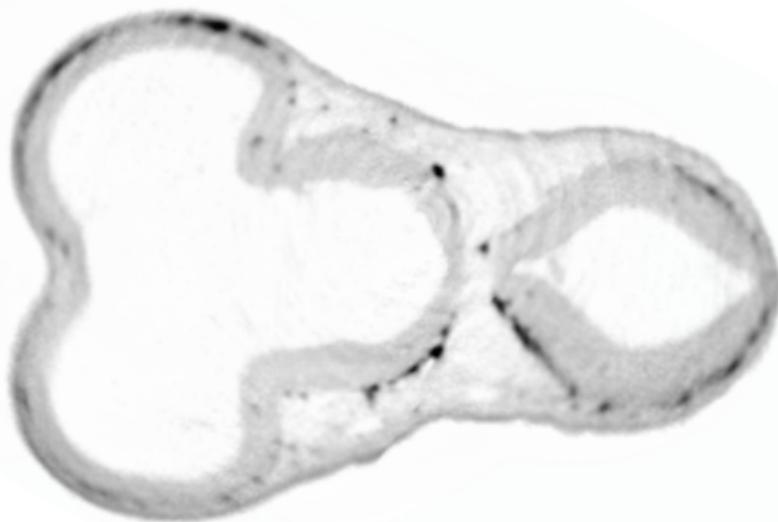
# Woolz Intervals and Tiles



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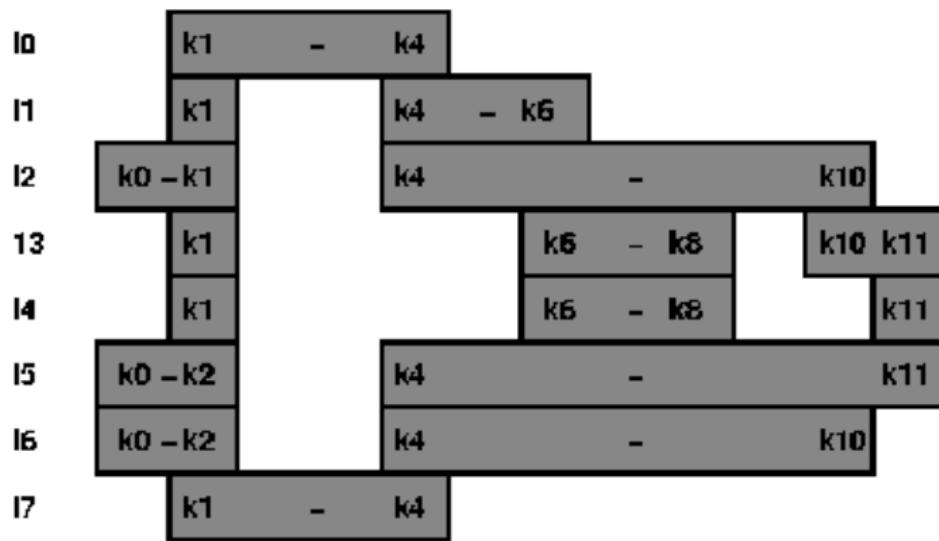
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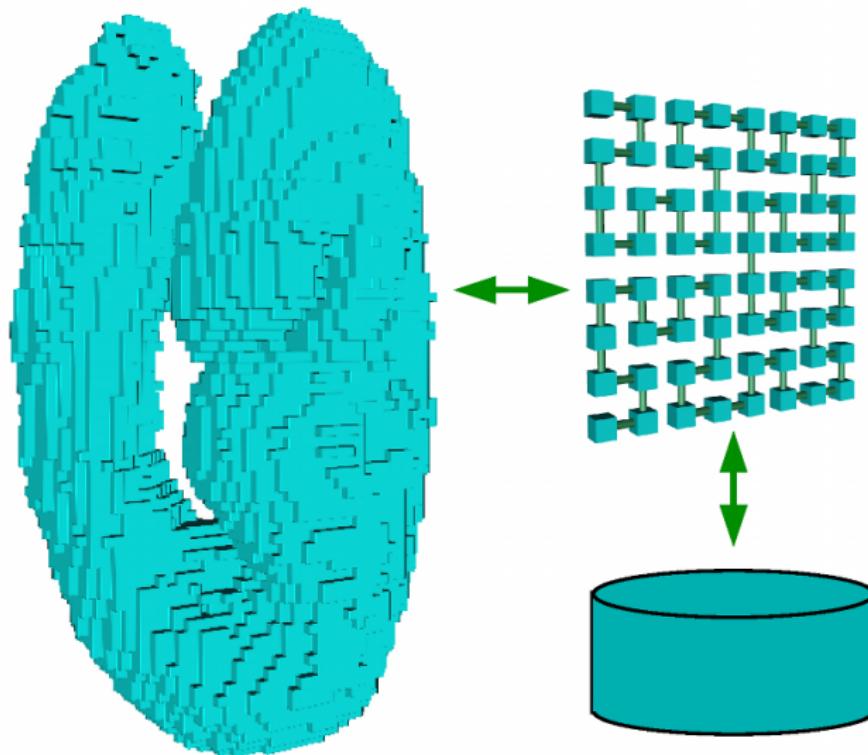
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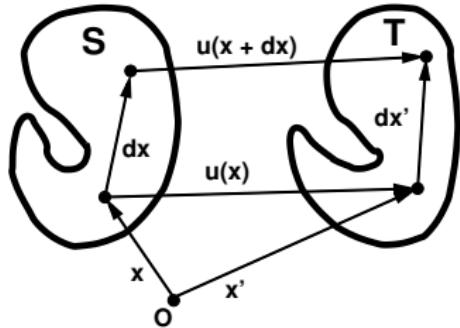
# Woolz Intervals and Tiles

- 0 → 1-4
- 1 → 1-1,4-6
- 2 → 0-1,4-10
- 3 → 1-1,6-8,10-11
- 4 → 1-1,6-8,11-11
- 5 → 0-2,4-11
- 6 → 0-2,4-10
- 7 → 1-4

# Woolz Intervals and Tiles



# Tensor Morphometry



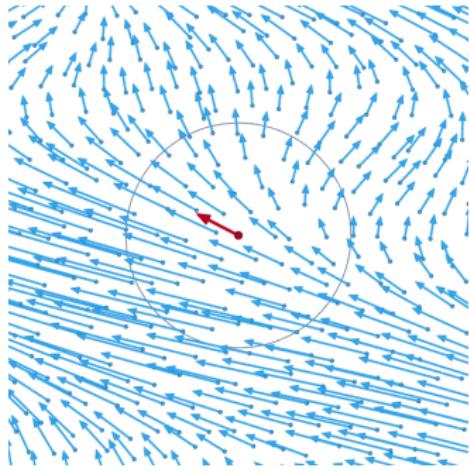
$$\mathbf{x}' + \mathbf{d}\mathbf{x}' = \mathbf{x} + \mathbf{d}\mathbf{x}' + \mathbf{u}(\mathbf{x} + \mathbf{d}\mathbf{x}')$$

$$\mathbf{d}\mathbf{x}' = \mathbf{d}\mathbf{x} + \nabla(\mathbf{u})\mathbf{d}\mathbf{x}$$

$$\epsilon_{ij} = \frac{1}{2} \left( \frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right)$$

$$\omega_{ij} = \frac{1}{2} \left( \frac{\partial u_i}{\partial x_j} - \frac{\partial u_j}{\partial x_i} \right)$$

# Tensor Morphometry



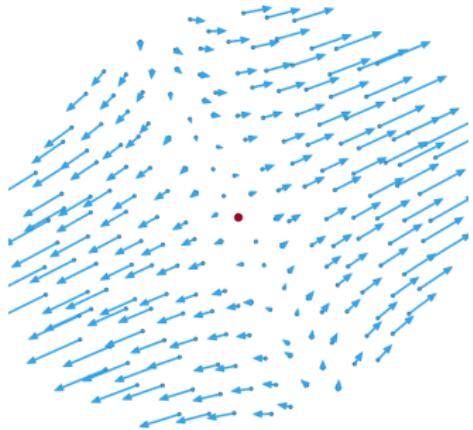
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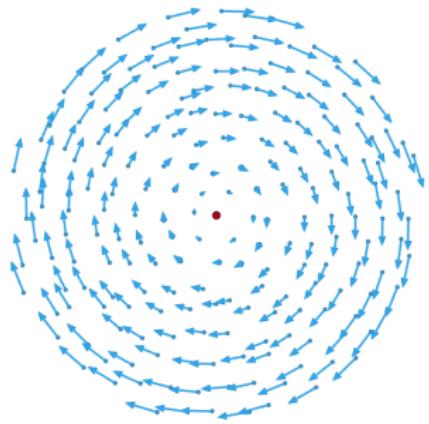
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